

Insights from GAN Training with Kernel Discriminators

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This talk includes joint work with: Parthe Pandit (UCSD+IIT Bombay), Sundeep Rangan (NYU), Alyson K. Fletcher (UCLA)

Motivation

Problem: Generative Adversarial Networks (GANs) are popular but hard to train

 Alternating min-max optimization for a non-convex objective is not fully understood

Contribution: Simple yet expressive framework to analyze convergence and failure modes

- MMD-GAN objective trained with gradient descent ascent
- Generator is unconstrained, discriminator is a kernel model



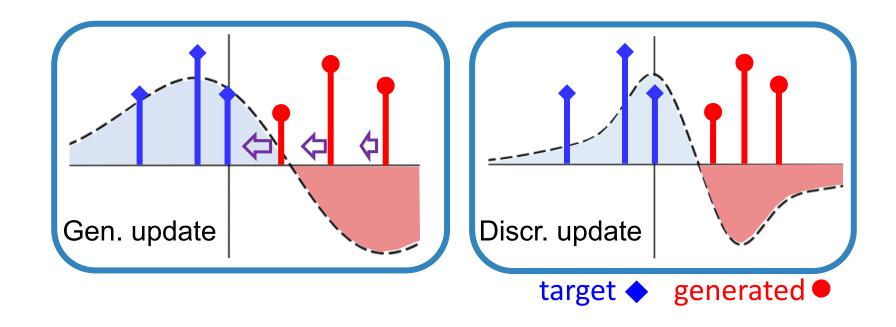
thispersondoesnotexist.com

Problem setup

Target and Generated Distributions: Directly parameterized by set of points (δ Dirac delta function):

$$\mathbb{P}_r(\boldsymbol{x}) = \sum_{i=1}^{N_r} p_i \delta(\boldsymbol{x} - \boldsymbol{x}_i), \quad \mathbb{P}_g(\boldsymbol{x}) = \sum_{j=1}^{N_g} \widetilde{p}_j \delta(\boldsymbol{x} - \widetilde{\boldsymbol{x}}_j),$$

Discriminator: $f: \mathcal{X} \to \mathbb{R}$ from a reproducing kernel hilbert space (RKHS) \mathcal{H}_K with positive definite kernel function $K: \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$.

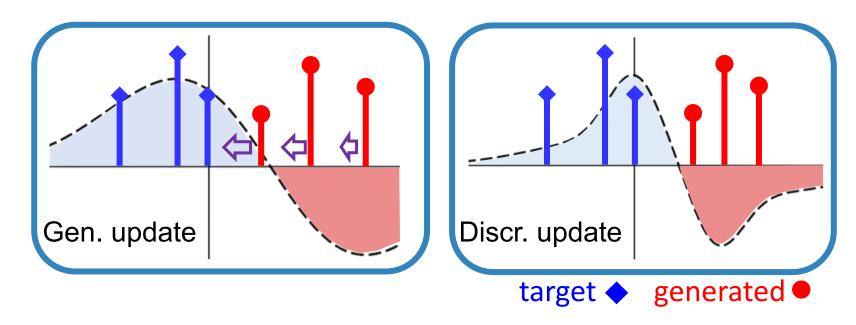


Problem setup

Optimization: $\min_{\widetilde{X}} \ \max_{f \in \mathcal{H}} \mathcal{L}(f, \widetilde{X})$ with loss defined as

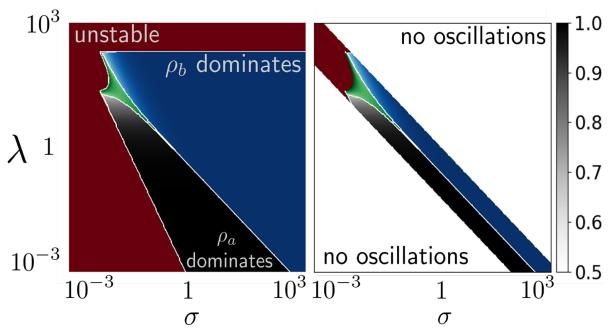
$$\mathcal{L}(f, \widetilde{\boldsymbol{X}}) := \sum_{i=1}^{N_r} p_i f(x_i) - \sum_{i=1}^{N_g} \widetilde{p}_i f(\widetilde{x}_j) - \frac{\lambda}{2} \|f\|_{\mathcal{H}}^2.$$

Note: Just maximizing the objective over $f \in \mathcal{H}$ results in the maximum mean discrepancy (MMD) between distributions, which is a common two-sample test statistic



First-Order Analysis

Idea: Look at some local region around each true point $oldsymbol{x}_i$



Dominating eigenvalues when using an RBF kernel discriminator

Insight 1 (Becker et al. 22): Existence of good local minima (exact convergence) and bad (mode collapse).

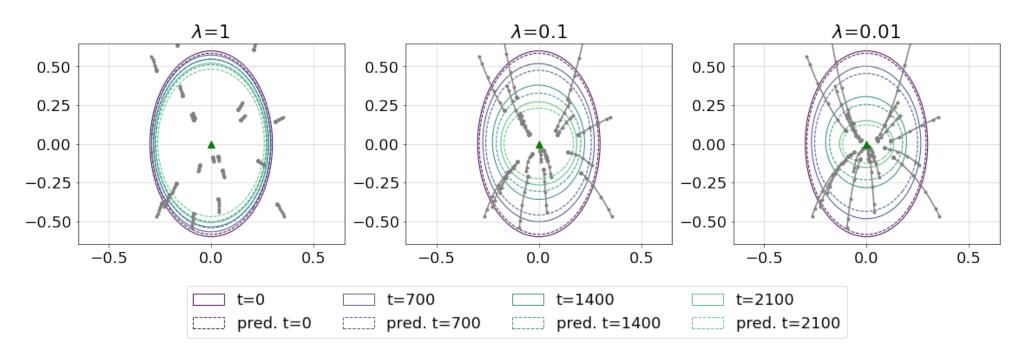
Insight 2 (Becker et al. 23): Analyze the *rate* of convergence by looking at eigenvalue functions. Can prescribe hyperparameters to achieve fastest local convergence.

hyperparameters: λ regularization, σ kernel width, η_g, η_d learning rates, $\Delta_i := p_i - \sum_{j \in N_i} \widetilde{p}_j$ local probability mass difference

Second-Order Analysis

Idea: Look at the first two moments (mean and variance) of the generated distribution

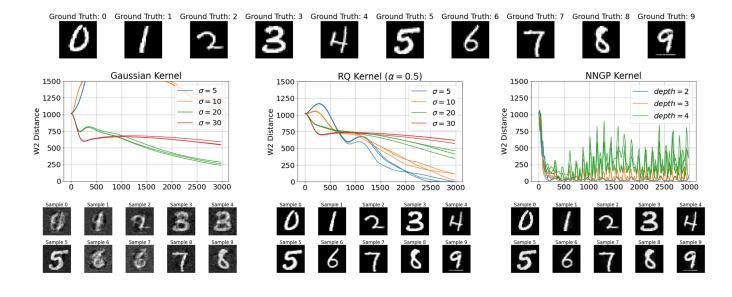
Predicted vs. Actual Covariance ($\sigma = 1$)



Insight 3: Smaller kernel width σ increases 'momentum' of convergence in second order analysis (stronger effect than linearized analysis predicts)

hyperparameters: λ regularization, σ kernel width, η_g, η_d learning rates, $\Delta_i := p_i - \sum_{j \in N_i} \widetilde{p}_j$ local probability mass difference

Key takeaways:



Why do we care?

- Neural networks can be thought of as kernel machines whose kernel shape evolves over time (evolves very little in NTK regime)
- Reducing effective kernel width of the discriminator during training promotes fast convergence to good minima, and is already done heuristically (Karras et. al 2018)!
- Min-max optimization is used outside of GANs, and techniques used here could be used to study other systems

Thank you!

Questions?

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